

# LM61 2.7V, SOT-23 or TO-92 Temperature Sensor General Description Applications

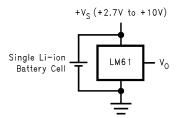
The LM61 is a precision integrated-circuit temperature sensor that can sense a  $-30^{\circ}$ C to  $+100^{\circ}$ C temperature range while operating from a single +2.7V supply. The LM61's output voltage is linearly proportional to Celsius (Centigrade) temperature ( $+10 \text{ mV/}^{\circ}$ C) and has a DC offset of +600 mV. The offset allows reading negative temperatures without the need for a negative supply. The nominal output voltage of the LM61 ranges from +300 mV to +1600 mV for a  $-30^{\circ}$ C to  $+100^{\circ}$ C temperature range. The LM61 is calibrated to provide accuracies of  $\pm 2.0^{\circ}$ C at room temperature and  $\pm 3^{\circ}$ C over the full  $-25^{\circ}$ C to  $+85^{\circ}$ C temperature range.

The LM61's linear output, +600 mV offset, and factory calibration simplify external circuitry required in a single supply environment where reading negative temperatures is required. Because the LM61's quiescent current is less than 125  $\mu$ A, self-heating is limited to a very low 0.2°C in still air. Shutdown capability for the LM61 is intrinsic because its inherent low power consumption allows it to be powered directly from the output of many logic gates.

#### Features

- Calibrated linear scale factor of +10 mV/°C
- Rated for full -30° to +100°C range
- Suitable for remote applications
- UL Recognized Component 91

## **Typical Application**



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#### $V_{O} = (+10 \text{ mV/}^{\circ}\text{C x T }^{\circ}\text{C}) + 600 \text{ mV}$

Temperature (T)	Typical V <sub>o</sub>		
+100°C	+1600 mV		
+85°C	+1450 mV		
+25°C	+850 mV		
0°C	+600 mV		
–25°C	+350 mV		
-30°C	+300 mV		



August 2005 M61 2.7V, SOT-23 or TO-92 Temperature Sensor (max) 4.0°C (max) +10 mV/°C 25 μA (max) 0.8°C (max)

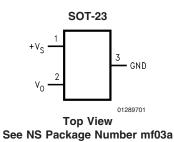
- Cellular Phones
- ComputersPower Supply M
- Power Supply ModulesBattery Management
- FAX Machines
- Printers
- Disk Drives
- Appliances

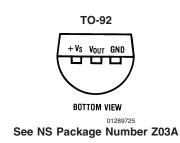
## **Key Specifications**

Accuracy at 25°C	±2.0 or ±3.0°C
	(max)
■ Accuracy for -30°C to +100°C	±4.0°C (max)
■ Accuracy for -25°C to +85°C	±3.0°C (max)
Temperature Slope	+10 mV/°C
Power Supply Voltage Range	+2.7V to +10V
Current Drain @ 25°C	125 µA (max)
Nonlinearity	±0.8°C (max)
<ul> <li>Output Impedance</li> </ul>	800 Ω (max)

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## **Connection Diagrams**





## **Ordering Information**

Order Number	Device Top Mark	Supplied In	Accuracy Over Specified Temperature Range (°C)	Specified Temperature Range	Package Type
LM61BIM3	T1B	1000 Units on Tape and Reel	± 3	–25°C to +85°C	— SOT-23
LM61BIM3X	T1B	3000 Units on Tape and Reel	S	-23 0 10 +03 0	
LM61CIM3	T1C	1000 Units on Tape and Reel	± 4	–30°C to +100°C	
LM61CIM3X	T1C	3000 Units on Tape and Reel	¥	-30 C 10 +100 C	
LM61BIZ	LM61BIZ	Bulk	± 3	–25°C to +85°C	TO-92
LM61CIZ	LM61CIZ	Bulk	± 4	-30°C to +100°C	10-92

#### Absolute Maximum Ratings (Note 1)

Supply Voltage	+12V to -0.2V
Output Voltage	(+V <sub>S</sub> + 0.6V) to
	–0.6V
Output Current	10 mA
Input Current at any pin (Note 2)	5 mA
Storage Temperature	–65°C to +150°C
Maximum Junction Temperature	
(T <sub>JMAX</sub> )	+125°C
ESD Susceptibility (Note 3) :	
Human Body Model	2500V
Machine Model	250V

#### Operating Ratings(Note 1)

Specified Temperature Range:	$\textbf{T}_{\textbf{MIN}} \leq \textbf{T}_{\textbf{A}} \leq \textbf{T}_{\textbf{MAX}}$
LM61C	$-30^{\circ}C \leq T_A \leq +100^{\circ}C$
LM61B	$-25^{\circ}C \leq T_A \leq +85^{\circ}C$
Supply Voltage Range (+V <sub>S</sub> )	+2.7V to +10V
Thermal Resistance, $\theta_{JA}$ (Note 5)	
SOT-23	450°C/W
TO-92	180°C/W

Soldering process must comply with National Semiconductor's Reflow Temperature Profile specifications. Refer to www.national.com/packaging. (Note 4)

### **Electrical Characteristics**

Unless otherwise noted, these specifications apply for  $+V_S = +3.0 V_{DC}$ . Boldface limits apply for  $T_A = T_J = T_{MIN}$  to  $T_{MAX}$ ; all other limits  $T_A = T_J = 25^{\circ}C$ .

Parameter	Conditions	Typical	LM61B	LM61C	Units
		(Note 6)	Limits	Limits	(Limit)
			(Note 7)	(Note 7)	
Accuracy (Note 8)			±2.0	±3.0	°C (max)
			±3.0	±4.0	°C (max)
Output Voltage at 0°C		+600			mV
Nonlinearity (Note 9)			±0.6	±0.8	°C (max)
Sensor Gain		+10	+9.7	+9.6	mV/°C (min)
(Average Slope)			+10.3	+10.4	mV/°C (max)
Output Impedance	$+3.0V \le +V_S \le +10V$		0.8	0.8	kΩ (max)
	$-30^{\circ}C \le T_{A} \le +85^{\circ}C, \ +V_{S} = +2.7V$		2.3	2.3	kΩ (max)
	$+85^{\circ}C \le T_{A} \le +100^{\circ}C, +V_{S} = +2.7V$		5	5	kΩ (max)
Line Regulation (Note 10)	$+3.0V \le +V_S \le +10V$		±0.7	±0.7	mV/V (max)
	$+2.7V \le +V_S \le +3.3V$		±5.7	±5.7	mV (max)
Quiescent Current	$+2.7V \le +V_S \le +10V$	82	125	125	μA (max)
			155	155	μA (max)
Change of Quiescent Current	$+2.7V \le +V_S \le +10V$	±5			μA
Temperature Coefficient of		0.2			µA/°C
Quiescent Current					
Long Term Stability (Note 11)	T <sub>J</sub> =T <sub>MAX</sub> =+100°C, for 1000 hours	±0.2			°C

Note 1: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is functional, but do not guarantee specific performance limits. For guaranteed specifications and test conditions, see the Electrical Characteristics. The guaranteed specifications apply only for the test conditions listed. Some performance characteristics may degrade when the device is not operated under the listed test conditions.

Note 2: When the input voltage  $(V_I)$  at any pin exceeds power supplies  $(V_I < GND \text{ or } V_I > +V_S)$ , the current at that pin should be limited to 5 mA.

Note 3: The human body model is a 100 pF capacitor discharged through a 1.5 kΩ resistor into each pin. The machine model is a 200 pF capacitor discharged directly into each pin.

Note 4: Reflow temperature profiles are different for lead-free and non-lead-free packages.

Note 5: The junction to ambient thermal resistance  $(\theta_{JA})$  is specified without a heat sink in still air.

**Note 6:** Typicals are at  $T_J = T_A = 25^{\circ}C$  and represent most likely parametric norm.

Note 7: Limits are guaranteed to National's AOQL (Average Outgoing Quality Level).

Note 8: Accuracy is defined as the error between the output voltage and +10 mV/°C times the device's case temperature plus 600 mV, at specified conditions of voltage, current, and temperature (expressed in °C).

Note 9: Nonlinearity is defined as the deviation of the output-voltage-versus-temperature curve from the best-fit straight line, over the device's rated temperature range.

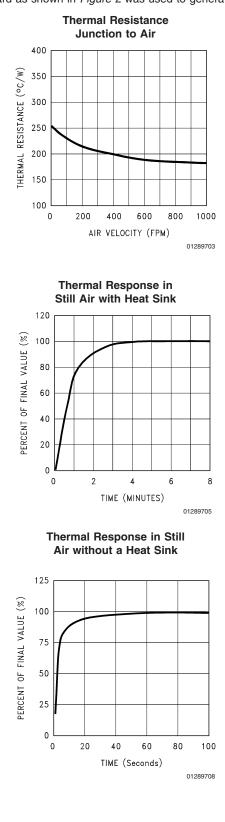
Note 10: Regulation is measured at constant junction temperature, using pulse testing with a low duty cycle. Changes in output due to heating effects can be computed by multiplying the internal dissipation by the thermal resistance.

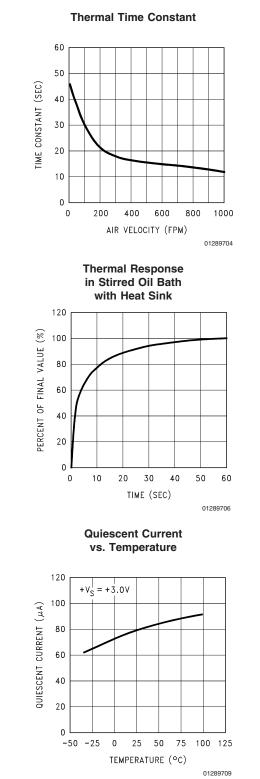
Note 11: For best long-term stability, any precision circuit will give best results if the unit is aged at a warm temperature, and/or temperature cycled for at least 46 hours before long-term life test begins. This is especially true when a small (Surface-Mount) part is wave-soldered; allow time for stress relaxation to occur. The majority of the drift will occur in the first 1000 hours at elevated temperatures. The drift after 1000 hours will not continue at the first 1000 hour rate.

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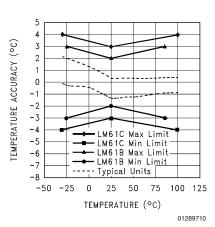
**Typical Performance Characteristics** The LM61 in the SOT-23 package mounted to a printed circuit board as shown in *Figure 2* was used to generate the following thermal curves.



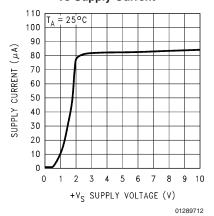


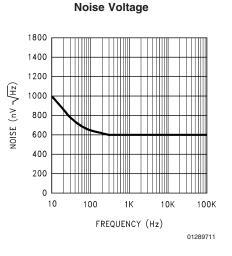
**Typical Performance Characteristics** The LM61 in the SOT-23 package mounted to a printed circuit board as shown in *Figure 2* was used to generate the following thermal curves. (Continued)

#### Accuracy vs Temperature

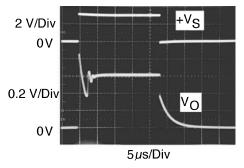


Supply Voltage vs Supply Current





#### Start-Up Response



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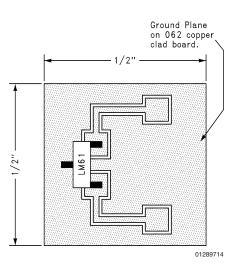


FIGURE 2. Printed Circuit Board Used for Heat Sink to Generate All Curves. <sup>1</sup>/<sub>2</sub>" Square Printed Circuit Board with 2 oz. Copper Foil or Similar.

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### 1.0 Mounting

The LM61 can be applied easily in the same way as other integrated-circuit temperature sensors. It can be glued or cemented to a surface. The temperature that the LM61 is sensing will be within about  $+0.2^{\circ}$ C of the surface temperature that LM61's leads are attached to.

This presumes that the ambient air temperature is almost the same as the surface temperature; if the air temperature were much higher or lower than the surface temperature, the actual temperature measured would be at an intermediate temperature between the surface temperature and the air temperature.

To ensure good thermal conductivity the backside of the LM61 die is directly attached to the GND pin. The lands and traces to the LM61 will, of course, be part of the printed circuit board, which is the object whose temperature is being measured.

Alternatively, the LM61 can be mounted inside a sealed-end metal tube, and can then be dipped into a bath or screwed into a threaded hole in a tank. As with any IC, the LM61 and

accompanying wiring and circuits must be kept insulated and dry, to avoid leakage and corrosion. This is especially true if the circuit may operate at cold temperatures where condensation can occur. Printed-circuit coatings and varnishes such as Humiseal and epoxy paints or dips are often used to ensure that moisture cannot corrode the LM61 or its connections.

The thermal resistance junction to ambient ( $\theta_{JA}$ ) is the parameter used to calculate the rise of a device junction temperature due to its power dissipation. For the LM61 the equation used to calculate the rise in the die temperature is as follows:

$$T_{J} = T_{A} + \theta_{JA} \left[ (+V_{S} I_{Q}) + (+V_{S} - V_{O}) I_{L} \right]$$

where  $I_{Q}$  is the quiescent current and  $I_{L}$  is the load current on the output. Since the LM61's junction temperature is the actual temperature being measured care should be taken to minimize the load current that the LM61 is required to drive.

The table shown in *Figure 3* summarizes the rise in die temperature of the LM61 without any loading with a 3.3V supply, and the thermal resistance for different conditions.

	SOT-23*		SOT-23**		TO-92*		TO-92***	
	no heat sink		small heat fin		no heat sink		small heat fin	
	θ <sub>JA</sub>	T <sub>J</sub> – T <sub>A</sub>	θ <sub>JA</sub>	T <sub>J</sub> – T <sub>A</sub>	θ <sub>JA</sub>	T <sub>J</sub> – T <sub>A</sub>	θ <sub>JA</sub>	T <sub>J</sub> – T <sub>A</sub>
	(°C/W)	(°C)	(°C/W)	(°C)	(°C/W)	(°C)	(°C/W)	(°C)
Still air	450	0.26	260	0.13	180	0.09	140	0.07
Moving air			180	0.09	90	0.05	70	0.03

\*Part soldered to 30 gauge wire.

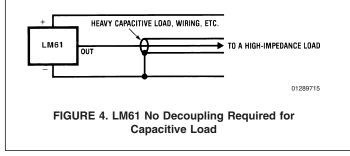
\*\*Heat sink used is 1/2" square printed circuit board with 2 oz. foil with part attached as shown in Figure 2.

\*\*\*Part glued and leads soldered to 1" square of 1/16" printed circuit board with 2oz. foil or similar.

FIGURE 3. Temperature Rise of LM61 Due to Self-Heating and Thermal Resistance ( $\theta_{JA}$ )

### 2.0 Capacitive Loads

The LM61 handles capacitive loading well. Without any special precautions, the LM61 can drive any capacitive load as shown in *Figure 4*. Over the specified temperature range the LM61 has a maximum output impedance of 5 k $\Omega$ . In an extremely noisy environment it may be necessary to add some filtering to minimize noise pickup. It is recommended that 0.1  $\mu$ F be added from +V<sub>S</sub> to GND to bypass the power supply voltage, as shown in Figure 5. In a noisy environment it may be necessary to add a capacitor from the output to ground. A 1  $\mu$ F output capacitor with the 5 k $\Omega$  maximum output impedance will form a 32 Hz lowpass filter. Since the thermal time constant of the LM61 is much slower than the 5 ms time constant formed by the RC, the overall response time of the LM61 will not be significantly affected. For much larger capacitors this additional time lag will increase the overall response time of the LM61.



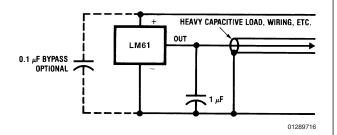
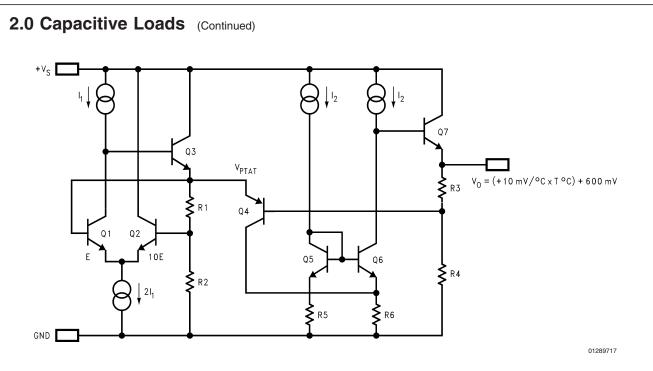


FIGURE 5. LM61 with Filter for Noisy Environment





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